



AN10386

Baud rate calculation for Philips 16C UARTs

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Application note

Document information

Info	Content
Keywords	baud rate, tolerance, frequency error
Abstract	This application note details how baud rates and baud rate tolerance are calculated and determined.

Revision history

Rev	Date	Description
AN10386_1	20050802	Application note. Initial version.

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1. Introduction

The purpose of this application note is to describe how baud rates and a crystal frequency can be determined for any Philips 16C UART. The equation for calculating the baud rates is listed in the data sheet section 'Programmable baud rate generator', but will be given here for reference. This equation is based on the fact that the UART samples the start bit at 16 times the baud rate. This 16× oversampling helps to determine the center of the start bit, and hence the center of all the bits that follow the start bit.

2. Baud rate calculation

The equation to calculate the baud rate is listed in [Equation 1](#):

$$\text{baud} = \frac{X1 \text{ freq}}{16 \times DIV} \quad (1)$$

where DIV is the number (in hex) to program the DLL and DLM. 'X1 freq' is the crystal's frequency or the frequency at XTAL1 pin of the UART.

From [Equation 1](#), it can be calculated that:

$$DIV = \frac{X1 \text{ freq}}{16 \times \text{baud}} \quad (2)$$

Also from [Equation 1](#) it can also be shown that:

$$X1 \text{ freq} = \text{baud} \times 16 \times DIV \quad (3)$$

The error between the 'baud' and 'baud (selected)' is given as:

$$\% \text{ error} = \frac{|\text{baud} - \text{baud (selected)}|}{\text{baud}} \times 100 \quad (4)$$

See the example in [Section 2.1.2](#), for 'baud (selected)'.

2.1 Examples using a 19.2 MHz clock

2.1.1 Example 1

Suppose that we want a 9600 baud rate, and we want to know the values to be written to DLL and DLM. From [Equation 2](#):

$$DIV = \frac{19.2M}{(16 \times 9600)} = 125$$

This number must be converted to hex before writing to DLL and DLM. A simple conversion shows the hex equivalent is 0x7D. Therefore, DLL must be written with 0x7D and DLM must be set to 0x00.

2.1.2 Example 2

Suppose that we want a 57600 baud rate, and we want to know the values to be written to DLL and DLM. Again from [Equation 2](#):

$$DIV = \frac{19.2M}{(16 \times 57600)} = 20.83$$

Because 20.83 is not an even number, we must round it up to the closest even number of 21. Using the formula from [Equation 1](#), we can calculate the new baud rate based on this number:

$$\text{baud (selected)} = \frac{19.2M}{(16 \times 21)} = 57142.86$$

This is not exactly what we want; we want 57600. Therefore the error is:

$$\% \text{ Error} = \frac{57600 - 57142.86}{57600} \times 100 = 0.79 \%$$

There is no exact limit on how much frequency error can be tolerated by the UART, since this depends on the baud rates, the precise frequencies used by the two devices, the character length, the number of stop bits, and whether a parity bit is used or not. However, most UARTs will work with a frequency error less than 5 %. This is the theoretical limit based on 16× sampling of the start bit, and 10-bit data format (one start bit, 8 data bits, and one stop bit).

2.1.3 Example 3

Suppose we select the UART to operate at 921.6 kbit/s, and we need to know what frequency is required. This frequency also depends on the setting of the DIV (DLL and DLM), assume that DLM is set to 0x00, and DLL is set to 0x01 for this example.

From [Equation 3](#):

$$\begin{aligned} X1 \text{ freq.} &= \text{baud} \times 16 \times DIV \\ &= 921.6 \text{ k} \times 16 \times 1 \\ &= 14.7456 \text{ MHz} \end{aligned}$$

3. Abbreviations

Table 1: Abbreviations

Acronym	Description
DLL	Divisor Latch L
DLM	Divisor Latch M
UART	Universal Asynchronous Receiver/Transmitter

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